

# CAD Algorithms

## Linear Programming

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## Linear Programming (LP)

- What is LP?
  - A Linear Program (LP) is a problem that can be expressed as follows (the so-called Standard Form):

```
minimize cx                // Objective Function
subject to Ax = b          // Constraints
x >= 0
```

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## LP

- $\mathbf{x}$  is the vector of variables to be solved for
- $\mathbf{A}$  is a matrix of known coefficients
- $\mathbf{c}$  and  $\mathbf{b}$  are vectors of known coefficients
- The expression " $\mathbf{c}\mathbf{x}$ " is called the objective function
- The equations " $\mathbf{A}\mathbf{x}=\mathbf{b}$ " are called the constraints
- The matrix  $\mathbf{A}$  is generally not square, hence we can't solve an LP by just inverting  $\mathbf{A}$ .
  
- LP tools (softwares) can handle both **minimization** and **maximization** problems.

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## LP

- The importance of linear programming derives in part from:
  - Its many applications
    - e.g. VLSI Physical Design
  - The existence of good general-purpose techniques (softwares) for finding optimal solutions.
    - CPLEX, LPSolve, AMPL, etc.
    - These techniques take as input only an LP in the above Standard Form, and determine a solution without reference to any information concerning the LP's origins or special structure.
    - They are fast and reliable over a substantial range of problem sizes and applications.

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## Integer Linear Programming (ILP)

- Integer programming (or integer linear programming) requires some or all of the variables to take **integer** (whole number) values.
- **Advantage:** Integer programs (IPs) often have the advantage of being more realistic than LPs.
  - It provides exact result
  - It is deterministic
- **Disadvantage:** IPs are much harder to solve.
- The most widely used general-purpose techniques (softwares) for solving IPs use the solutions to a series of LPs to manage the search for integer solutions and to prove optimality.

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## ILP vs. LP

- Variables are constructed to take integer values.
- ILP is very much harder problem than ordinary LP.
- In both theory and practice, ILP is more realistic.
- Many VLSI physical design problems are ILP problems, e.g. Floorplanning.

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## Tools/Softwares

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- **Lpsolve**
  - <http://www.geocities.com/lpsolve/>
- **AMPL**
  - <http://www.AMPL.com/>
- **CPLEX**
  - <http://www.ilog.com/products/cplex/>
- There is a lot more ...

## Example

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- Example from AMPL book:
  - Product A and B
  - Tons per hour:
    - A: 200
    - B: 140
  - Profit per ton:
    - A: \$25
    - B: \$30

## Cont.

- Maximum tons:

- A: 6000
- B: 4000

- **Question:**

- For 40 hours of production time, how many tons of A and how many tons of B should be produced to bring in the maximum profit?

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## Cont.

- **Answer:**

- Variables:
  - A or  $X_A$  (tons of A?)
  - B or  $X_B$  (tons of B?)

- The total hours to produce all these tons is given by:

(hours to make a ton of A)  $\cdot X_A$  + (hours to make a ton of B)  $\cdot X_B$

$$(1/200) \cdot X_A + (1/140) \cdot X_B \leq 40$$

$$0 \leq X_A \leq 6000$$

$$0 \leq X_B \leq 4000$$

**Profit:** (Profit per ton of A)  $\cdot X_A$  + (Profit per ton of B)  $\cdot X_B = 25X_A + 30X_B$

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## Cont.

- Linear Program:

$$\text{Maximize } 25X_A + 30X_B$$

Subject to:

$$(1/200)X_A + (1/140)X_B \leq 40$$

$$0 \leq X_A \leq 6000$$

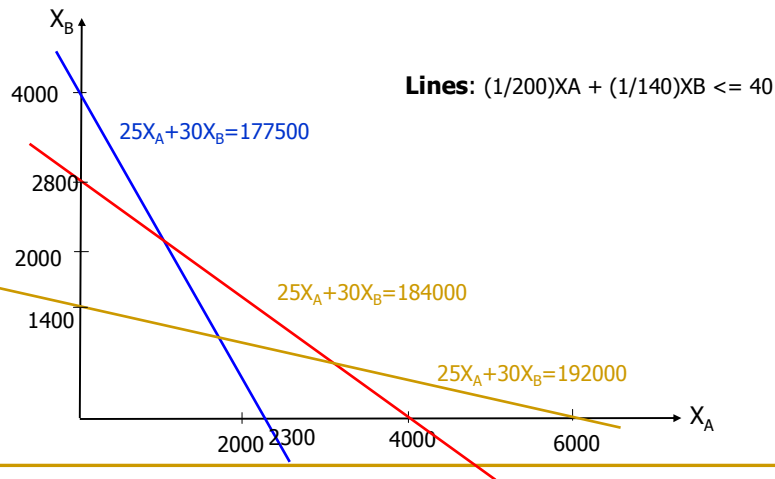
$$0 \leq X_B \leq 4000$$

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## Cont.

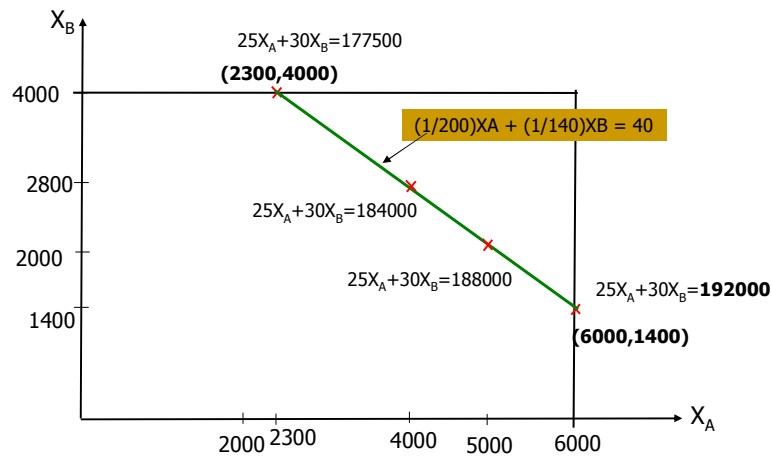
Maximize  $25X_A + 30X_B$ , Subject to:  $(1/200)X_A + (1/140)X_B \leq 40$ ,  $0 \leq X_A \leq 6000$ ,  $0 \leq X_B \leq 4000$



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## Constraint and Search Space



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## Linear Program in AMPL

```
Var XA
Var XB
Maximize Profit: 25*XA + 30*XB;
Subject to Time: (1/200)*XA + (1/140)*XB <= 40;
Subject to A Limit: 0 <= XA <= 6000;
Subject to B Limit: 0 <= XB <= 4000;
```



Store it in p1.mod

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## Cont.

- Then type these commands:

```
ampl: model p1.mod
```

```
ampl: solve
```

```
2 iterations, objective: 192000
```

```
ampl: display XA and XB
```

```
XA = 6000
```

```
XB = 1400
```

```
ampl: quit
```

## Example Problems

- Job Scheduling
  - Try the example shown in previous lecture
- Floorplanning
- Scheduling chips under test to control power
- Scheduling design with various delays
- Scan cell reordering



## Non-Linear Programming (NLP)

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minimize  $F(x)$

subject to:

$$g_i(x) = 0 \text{ for } i = 1, \dots, m_1 \text{ where } m_1 \geq 0$$

$$h_j(x) \geq 0 \text{ for } j=1, \dots, m \text{ where } m \geq m_1$$

- Genetic and Simulated Annealing Algorithms are categorized in NLP.