

# ECE6095: CAD Algorithms

## Optimization Techniques

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## Optimization Techniques

- Objective:
  - A basic review of complexity
  - Review of basic algorithms
  - Some physical design examples
  - Study of algorithms that are useful in the VLSI Design Automation
  
  - Students must be familiar with algorithms to be able to understand and solve physical design problems.
  
  - Students can use optimization techniques in their research and projects.

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## Combinatorics

- One of the fastest growing areas of applied mathematics.
- It is concerned with the study of arrangements, patterns, designs, assignments, schedules, connections, and configurations.
- **It is everyday science!!**
  - Class scheduling
  - Traveling salesman
  - Pattern recognition
  - Airline
  - Tours
  - **VLSI ...**

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## Optimization Problem

- A combinatorial optimization problem is defined as the set of all the instances of the problem, each instance being defined as a pair  $(F, c)$ .
  - $F$  is any set, the domain of feasible points
  - $c$  is the cost function
$$c: F \longrightarrow \mathbb{R}^l$$
  - The problem is to find an  $f \in F$  for which
$$c(f) \leq c(y) \text{ for all } y \in F$$
$$f \text{ is called globally optimal solution.}$$
- *Most VLSI problems belong to this class*

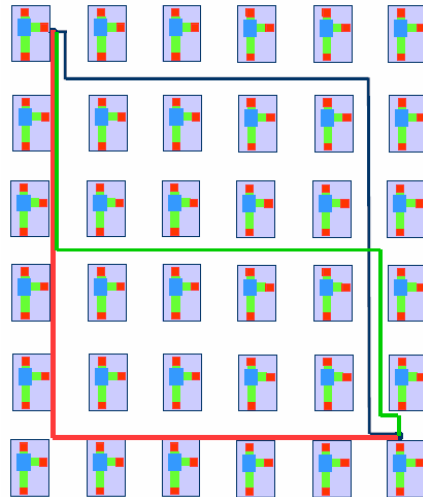
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## A VLSI Kind of Example

### Routing problem:

How to optimally connect  $\geq 2$  nodes in the circuit layout?



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## Computational Complexity

- How fast will an algorithm run on a computer?
- How much memory will it need?
- Computational complexity tries to answer these questions without having to deal with specific hardware.
- Thus exact seconds and megabytes are insignificant.
- **“input size”** is the base parameter that defines complexity.

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## Analyzing Algorithms

- Analysis results in a viable candidate algorithm for solving a problem.
- Analysis is challenging and requires knowledge tools like combinatorics, some probability, mathematical skills etc.
- While we will not spend rest of the semester to learn these skills, it is important to know **basics for appreciating the algorithm design(s)**.

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## Basic Algorithm Analysis

- How can we calculate the running time of an algorithm?
- How can we compare two different algorithms?
- How do we know if an algorithm is **optimal**?
- Count the number of **basic operations** performed by the algorithm on the **worst-case input**
- Basic operation:
  - An assignment
  - A comparison between two variables
  - An arithmetic operation between two variables
- The **worst-case input** is the input assignment for which the most basic operations are performed.

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## Input Size and Run Time

- Number of items that are input to the problem define input size.
  - Example sorting, addition, multiplication, etc.
- The running time of an algorithm is the number of primitive operations or “steps” that are executed.
- The running time of an algorithm varies with the input and typically grows with the input size.

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## Analysis

- Best Case
- Worst Case
- Average Case
  - Usually we are more interested in worst case analysis as it also defines the **upper bound** on the running time of an algorithm.
  - Average case analysis is interesting but for a large class of problems average case is as bad as worst case.
  - Average case is difficult to determine
- We focus on the worst case running time
  - Easier to analyze
  - Crucial to some applications such as physical design problems

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## Big-O Notation

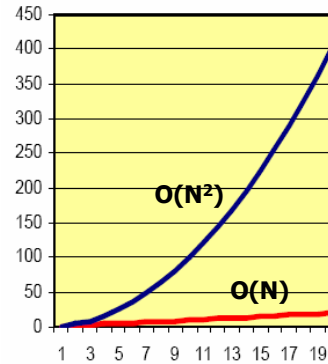
- **Big-O** is used for defining the upper bound on a function.
- We express complexity of the algorithms using **big-O notation**.
- For a problem of size  $N$  (Assume  $N$  is input):
  - A constant-time method is "order 1":  $O(1)$
  - A linear-time method is "order  $N$ ":  $O(N)$
  - A quadratic-time method is "order  $N$  squared":  $O(N^2)$
  - Cubic:  $O(N^3)$
  - Logarithmic,  $O(\log N)$

## How to Determine Complexities?

- Q: In general, how can we determine the running time of a piece of code?
- A: It depends on what kinds of statements are used.
- We don't need to count the exact number of steps in a program.
- **What matters is how that number grows with the size of the input to the program.**

## Rate of Growth of an Algorithm

- It is the rate of growth of running time of an algorithm that interests us the most, especially the CAD tool developers.
- Note that the  $O(N)$  algorithm takes more time than the  $O(N^2)$  algorithm for small inputs.
- As  $N$  grows, the  $O(N)$  algorithm takes less and less time relative to the  $O(N^2)$  algorithm. So for large  $N$ , **constant factors** don't matter, just the big-O bounds.

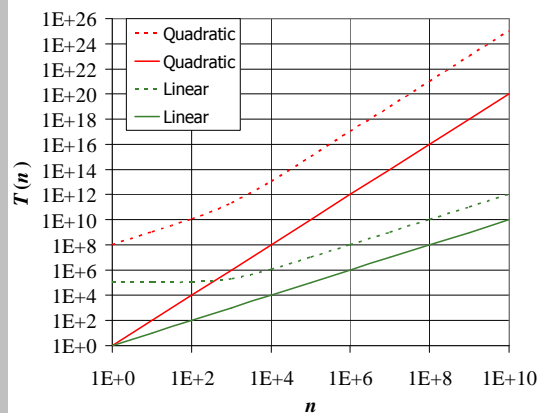


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## Constant Factors

- The growth rate is not affected by
  - constant factors or
  - lower-order terms
- Examples:
  - $10^2n + 10^5$  is a linear function:  $O(n)$
  - $10^5n^2 + 10^8n$  is a quadratic function:  $O(n^2)$
  - As  $n$  grows large,  $n^2$  will dominate



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## Rate of Growth of an Algorithm

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- Polynomial vs. Exponential
  - tractable vs. intractable
- Linear vs. Quadratic
  - execution realism in VLSI

## Tractable and Intractable

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- A problem that is solved in **deterministic polynomial** time is called **tractable**.
- A ***polynomial-time algorithm*** is defined to be an algorithm whose execution time is given by a polynomial on the size of the input.
- Problems that can't be solved by a polynomial-time algorithm are called ***intractable*** problems.
- NP complete problems are likely to be ***intractable***.



# CAD Algorithms

## Local and Global Optima

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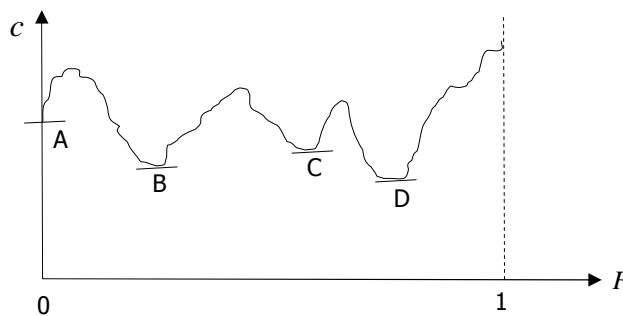


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## Local and Global Optima

- Finding globally optimal solution can be prohibitively difficult.



$c(f) \leq c(g) \quad f \in F \text{ and } g \in N(f)$ ,  $f$  is called locally optimal.

$N(f)$  is called Neighborhood function

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## Cont.

- A, B, C, and D are all locally optimal.
- Only D is globally optimal.
  
- $F$  and  $c$  are given.
- Evaluating the entire search space when  $F$  is large is infeasible.
- The goal of every algorithm is to find the global optima without searching entire search space.
- Most of the algorithms get stuck in local optima.

## Global Optimization

- The objective of global optimization is to find the globally best solution of models, in the (possible or known) presence of multiple local optima.
  
- The main question is how to find the global optima.